

# Deep Learning–Based Machine Vision System for In–Line Monitoring of High–Shear Wet Granulation Processes

Andraž Mehle<sup>1</sup>, Domen Kitak<sup>1</sup>, Ana Baumgartner<sup>2</sup>, Dejan Tomažević<sup>1,3</sup>

<sup>1</sup>Sensum, Computer Vision Systems, Ljubljana, Slovenia ✕ <sup>2</sup>Faculty of Pharmacy, University of Ljubljana, Slovenia ✕

<sup>3</sup>Faculty of Electrical Engineering, University of Ljubljana, Slovenia ✕ More info: [andraz.mehle@sensum.eu](mailto:andraz.mehle@sensum.eu)



## Aim

**Develop a machine vision system for in–line monitoring of high–shear granulation processes to provide a more reliable and continuous solution for assessing the state of granulation.**

## Introduction

Granulation is critical for pharmaceutical production, but inherently complex and poorly understood. Technologists rely in part on the visual appearance of granules, but this requires extensive training and can be inconsistent. With recent advances in deep learning, machine vision could be used for quantitative process end–point determination [1, 2].



Figure 1: Granule appearance at various states of granulation.

## Materials and Methods

### Granulation

We granulated a 2.2:1 mixture of mesoporous silica and isomalt with water in a laboratory–scale high–shear mixer. Three repetition runs were performed at 125 rpm mixer speed, 1000 rpm chopper speed and ~1.8 g/min water addition rate. The end–point was determined based on the impeller torque and the operator’s visual examination of the product.

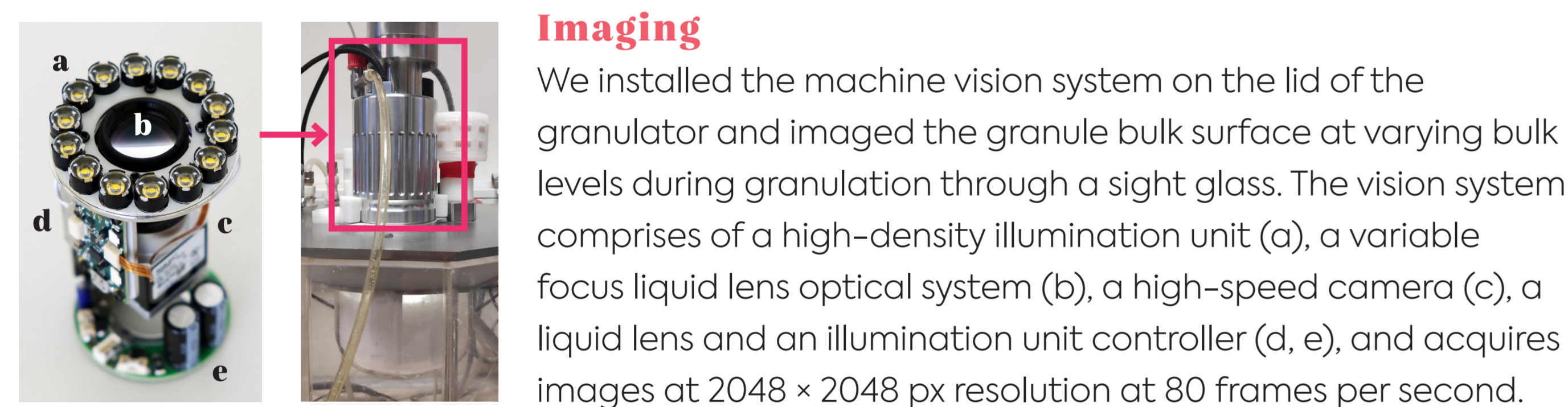


Figure 2: Bare machine vision system (left). High–shear mixer with the installed machine vision system (right).

### Imaging

We installed the machine vision system on the lid of the granulator and imaged the granule bulk surface at varying bulk levels during granulation through a sight glass. The vision system comprises of a high–density illumination unit (a), a variable focus liquid lens optical system (b), a high–speed camera (c), a liquid lens and an illumination unit controller (d, e), and acquires images at 2048 × 2048 px resolution at 80 frames per second.

### Image analysis

We used a customized convolutional neural network architecture from the VGG family [3] for predicting the granulation process state, formulated as binary classification:

- We defined two critical time periods within the process, i.e. a period of non–granulated and a period of optimally–granulated material.
- We trained the model on a fraction of the acquired images from the first process (reference).
- Predicted values close to 1 when material is optimally granulated and close to 0 otherwise.

### Evaluation

We tested the model on the test images from the reference process (proof of concept) and on the images from the second and the third granulation processes (generalization test).

## Results and Discussion

- The trained neural network accurately recognized the images within the time period of optimally granulated material for all three runs, with predicted values close to 1.
- Predicted values for the entire dry mixing phase and most of the wetting phase were close to 0, correctly indicating non or sub–optimally granulated material.
- The model meaningfully assessed the critical transition phase, where the appearance of granules changes substantially in a short period of time.
- The model predicted a time offset in granulation end–point for the second process, consistent with impeller torque measurements.
- The torque measurements show high standard deviation and can be unreliable for the determination of the optimal granulation state.
- **The trained neural network showed good generalization between individual process runs, confirming the suitability of the chosen approach and giving it practical value.**

## Conclusion

The study confirmed the feasibility of using machine vision and deep learning to evaluate the state of granulation and determine the optimal granulation endpoint in–line.

**This novel approach has the potential to significantly improve the efficiency and consistency of the high–shear granulation processes, leading to improved quality and reduced development costs of pharmaceutical products.**

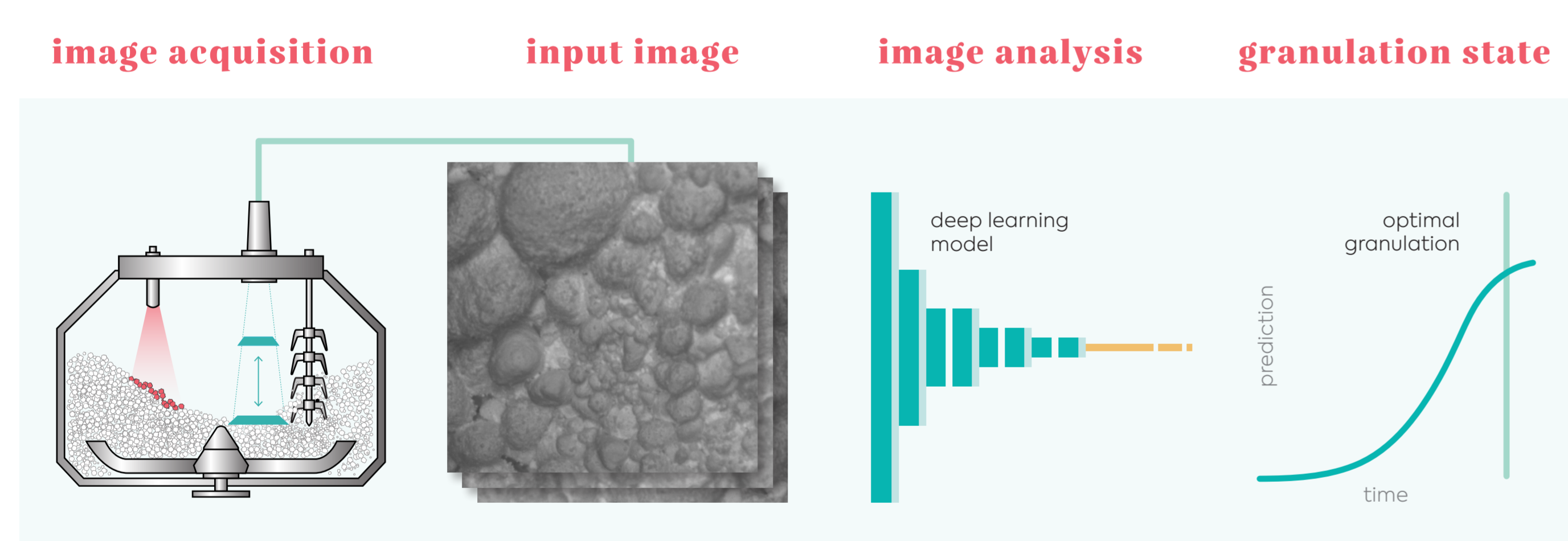


Figure 3: The major stages of the proposed approach.

process phase	dry mixing	wetting	wetting
process time	-156 to -15 s	0–2910 s	2910–2970 s
image index	-12480 to -1180	0–232820	232820–237620
process state	non–granulated	sub–optimally granulated	optimally granulated
training target	0	undefined	1
example image			

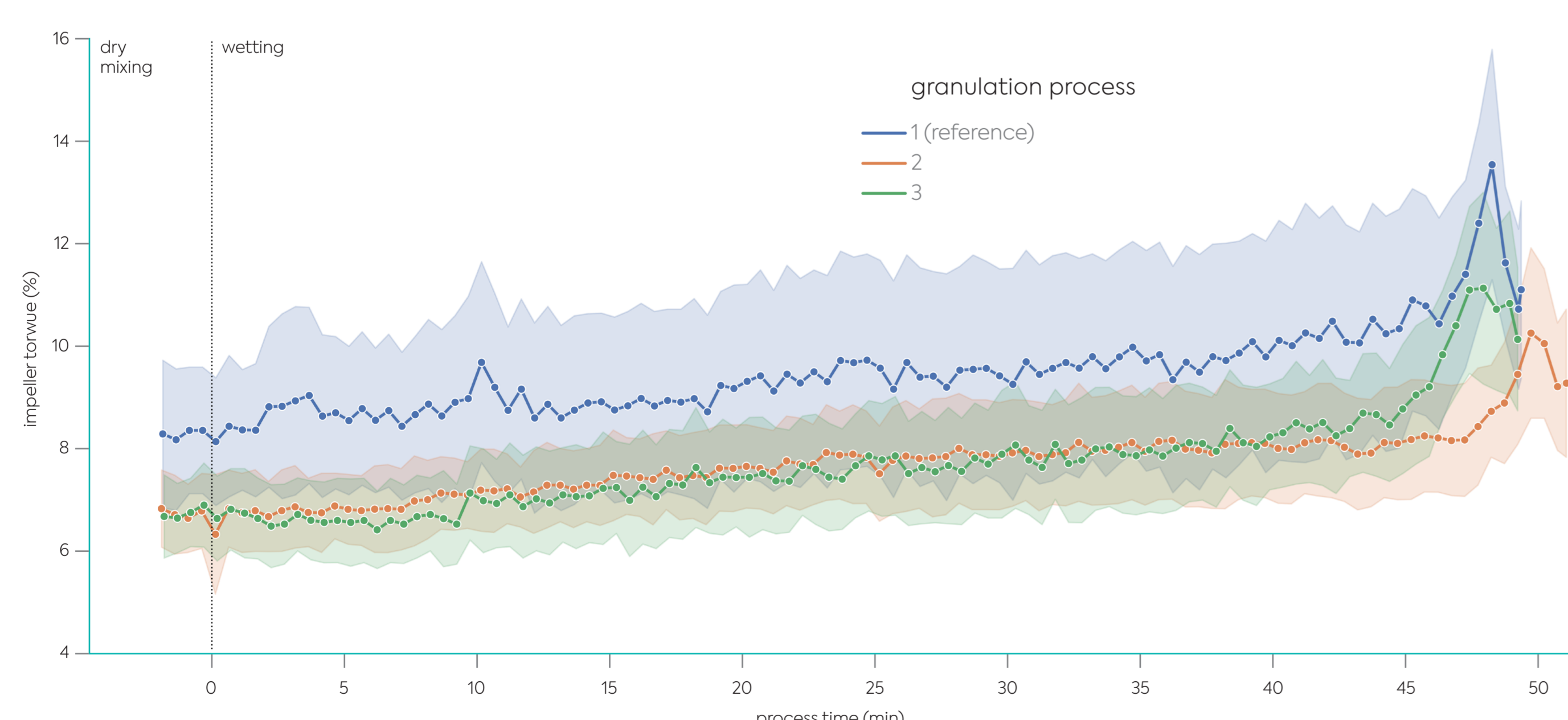


Figure 4: Impeller torque over process time for the three granulation processes.

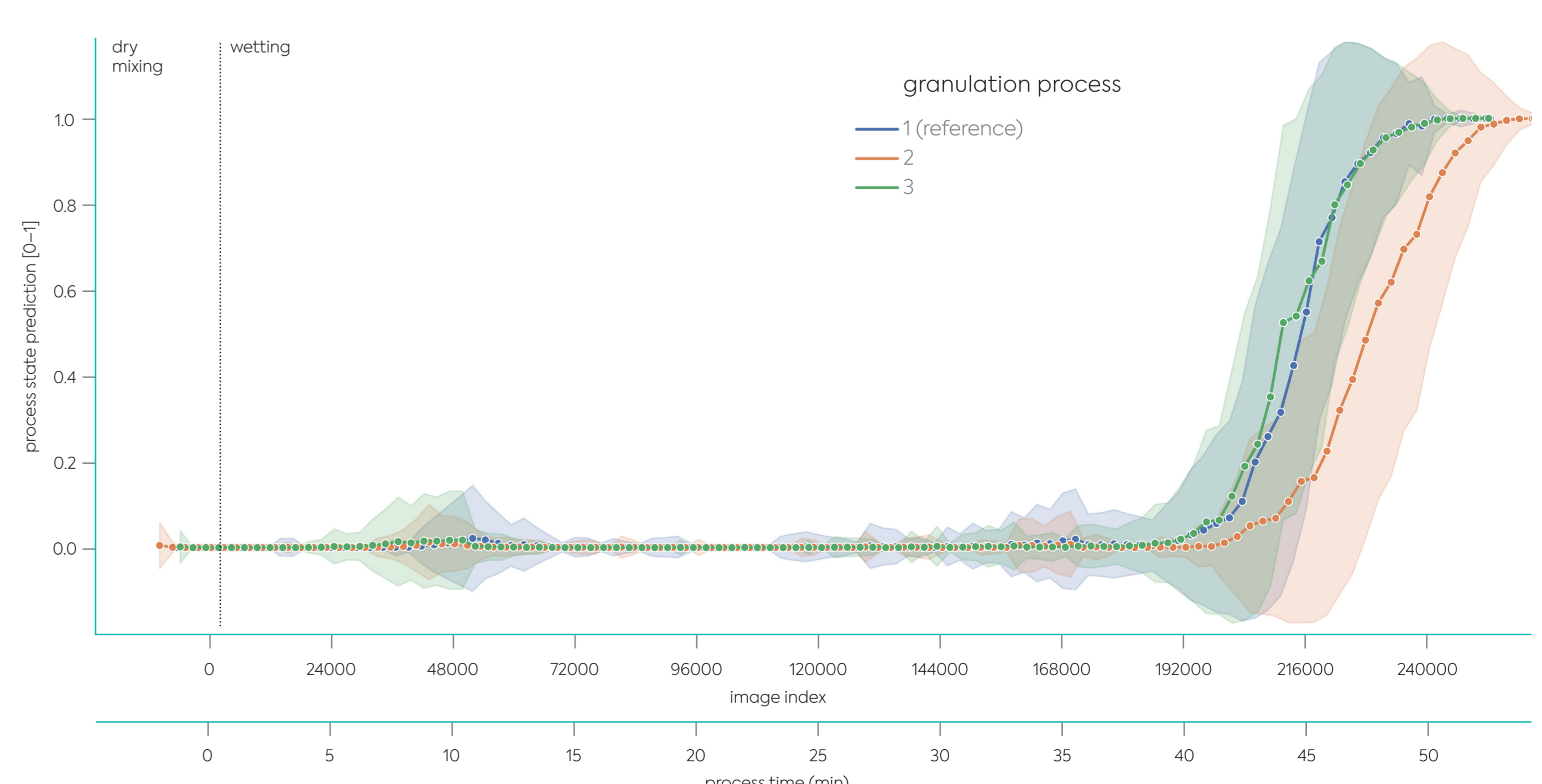


Figure 5: Predicted process state over time for the three processes, using the model trained on process 1 (reference).

## References

- [1] Mehle, D. Kitak, D. Rački, and D. Tomažević. “Deep Learning–Based Machine Vision System for Use in High–Shear Granulation”, 36th IFPAC, Jun. 2022, doi: 10.13140/RG.2.2.17241.39522, available from: [https://lit.fe.uni-lj.si/data/publications/pdf/Mehle-Tomazevic\\_IFPAC\\_2022.pdf](https://lit.fe.uni-lj.si/data/publications/pdf/Mehle-Tomazevic_IFPAC_2022.pdf)
- [2] G. Podrekar, D. Kitak, U. Urnaut, A. Mehle, S. Vidovič, P. Usenik, et al., “In–line monitoring of a high–shear granulation process using digital imaging,” 11th PBP, Mar. 2018, doi: 10.13140/RG.2.2.15212.21129, available from: <https://search.datacite.org/works/10.13140/RG.2.2.15212.21129>
- [3] K. Simonyan and A. Zisserman, “Very Deep Convolutional Networks for Large–Scale Image Recognition,” arXiv:1409.1556 [cs], Sep. 2014, available from: <http://arxiv.org/abs/1409.1556>